

# Package ‘vistla’

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**Title** Detecting Influence Paths with Information Theory

**Version** 2.0.1

**Description** Traces information spread through interactions between features, utilising information theory measures and a higher-order generalisation of the concept of widest paths in graphs. In particular, 'vistla' can be used to better understand the results of high-throughput biomedical experiments, by organising the effects of the investigated intervention in a tree-like hierarchy from direct to indirect ones, following the plausible information relay circuits. Due to its higher-order nature, 'vistla' can handle multi-modality and assign multiple roles to a single feature.

**License** GPL (>= 3)

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branches	<i>Extract all branches of the Vistla tree</i>
----------	--

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### Description

Gives access to a list of all branches in the tree.

### Usage

```
branches(x, suboptimal = FALSE)
```

```
## S3 method for class 'vistla'
as.data.frame(x, row.names = NULL, optional = FALSE, suboptimal = FALSE, ...)
```

### Arguments

x	vistla object.
suboptimal	if TRUE, sub-optimal branches are included.
row.names	passed to <code>as.data.frame</code> .
optional	passed to <code>as.data.frame</code> .
...	ignored.

### Value

A data frame collecting all branches traced by `vistla`. Each row corresponds to a single branch, i.e., edge between feature pairs. This way it is a triplet of original features, names of which are stored in `a`, `b` and `c` columns. For instance, path  $I \rightarrow J \rightarrow K \rightarrow L \rightarrow M$  would be stored in three rows, for  $(a, b, c) = (I, J, K)$ ,  $(J, K, L)$  and  $(K, L, M)$ . The width of a path (minimal  $\iota$  value) between root and feature pair  $(b, c)$  is stored in the `score` column. `depth` stores the path depth, starting from 1 for pairs directly connected to the root, and increasing by one for each additional feature. Final column, `leaf`, is a logical path indicating whether the edge is a final segment of the widest path between root and `c`.

### Note

Pruned trees (obtained with `prune` and using `targets` argument in the `vistla` call) have no sub-optimal branches.

---

`cchain`*Synthetic continuous data representing a simple mediator chain*

---

**Description**

Chain is generated from an uniform variable  $X$  by progressively adding gaussian noise, producing a mediator chain identical to this of the `chain` data, i.e.,

$$X \rightarrow M_1 \rightarrow M_2 \rightarrow M_3 \rightarrow M_4 \rightarrow Y$$

The set consists of 20 observations, and is tuned to be easily deciphered.

**Usage**

```
data(cchain)
```

**Format**

A data set with six numerical columns.

---

`chain`*Synthetic data representing a simple mediator chain*

---

**Description**

Chain is generated from a simple Bayes network,

$$X \rightarrow M_1 \rightarrow M_2 \rightarrow M_3 \rightarrow M_4 \rightarrow Y$$

where every variable is binary. The set consists of 11 observations, and is tuned to be easily deciphered.

**Usage**

```
data(chain)
```

**Format**

A data set with six binary factor columns.

---

 flow

*Construct the value for the flow*


---

### Description

Vistla builds the tree by optimising the influence score over path, which is given by the `iota` function. The `flow` argument of the `vistla` function can be used to modify the default `iota` and some associated behaviours. This function can be used to construct the proper value of this argument.

### Usage

```
flow(code, ..., from = TRUE, into = FALSE, down, up, forcepath)
```

```
## S3 method for class 'vistla_flow'
print(x, ...)
```

### Arguments

<code>code</code>	Character code of the flow parameter, like "fromdown". If given, overrides other arguments.
<code>...</code>	ignored.
<code>from</code>	if TRUE, paths must satisfy data processing inequality as going from the root.
<code>into</code>	if TRUE, paths must satisfy data processing inequality as going into the root.
<code>down</code>	if TRUE, subsequent features on the path must have lower mutual information with the root; by default, true when <code>from</code> is true but if both <code>from</code> and <code>into</code> are true. Can't be true together with <code>up</code> .
<code>up</code>	if TRUE, subsequent features on the path must have higher mutual information with the root; by default, true when <code>into</code> is true but if both <code>from</code> and <code>into</code> are true. Can't be true together with <code>down</code> .
<code>forcepath</code>	when neither <code>up</code> or <code>down</code> is true, <code>vistla</code> may output walks rather than paths, i.e., sequences of features which are not unique. Yet, when this argument is set to TRUE, additional condition is checked to forbid such self-intersections. One should note that this check is computationally expensive, though. By default true when both <code>up</code> and <code>down</code> are false.
<code>x</code>	flow value to print.

### Value

A `vistla_flow` object which can be passed to the `vistla` function; in practice, a single integer value.

---

hierarchy	<i>Extract the vertex hierarchy from the vistla tree</i>
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---

**Description**

Traverses the vistla tree in a depth-first order and lists the visited vertices as a data frame.

**Usage**

```
hierarchy(x)
```

**Arguments**

x                   vistla object.

**Value**

A data frame of a class vistla\_hierarchy.

**Note**

This function effectively prunes the tree off suboptimal paths.

---

junction	<i>Synthetic data representing a junction</i>
----------	---

---

**Description**

Junction is a model of a multimodal agent, a variable that is an element of multiple separate paths. Here, these paths are  $A_1 \rightarrow X \rightarrow A_2$  and  $B_1 \rightarrow X \rightarrow B_2$ , while  $X$  is the junction. The set consists of 12 observations, and is tuned to be easily deciphered.

**Usage**

```
data(junction)
```

**Format**

A data set with five factor columns.

---

leaf_scores	<i>Extract leaf scores of vertex pairs</i>
-------------	--

---

**Description**

Produces a matrix  $S$  where  $S_{ij}$  is a score of the path ending in vertices  $i$  and  $j$ . Since vistla works on vertex pairs, this value is unique. This can be interpreted as a feature similarity matrix in context of the current vistla root.

**Usage**

```
leaf_scores(x)
```

**Arguments**

x                   vistla object.

**Value**

A square matrix with leaf scores of all feature pairs.

**Note**

This function should be called on an unpruned vistla tree, otherwise the result will be mostly composed of zeroes.

---

mi_scores	<i>Extract mutual information score matrix</i>
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---

**Description**

Produces a matrix  $S$  where  $S_{ij}$  is a value of  $I(X_i; X_j)$ . This matrix is always calculated as an initial step of the vistla algorithm and stored in the vistla object.

**Usage**

```
mi_scores(x)
```

**Arguments**

x                   vistla object.

**Value**

A symmetric square matrix with mutual information scores between features and root.

**Description**

One can use this function for a quick, ad hoc discretisation of numerical features in a data frame, so that it could be passed to `vistla` using the maximal likelihood estimation (mle, the default). This can be used to simulate legacy behaviour of `vistla`, which was to automatically perform such conversion with 10 equal-width bins. The non-numeric columns are left as they were, hence this function is idempotent and does nothing when given fully discrete data.

**Usage**

```
mle_coerce(x, bins = 3, equal = c("size", "width"))
```

**Arguments**

<code>x</code>	Data frame to be converted.
<code>bins</code>	Number of bins to cut each numerical column into.
<code>equal</code>	If given "width", function performs cuts into bins of an equal width, which may thus contain substantially different number of objects. On the other hand, when given "size" (default), cuts are done according to quantiles, hence provide bins with approximately the same number of objects, yet with different widths. Both options are asymptotically equivalent when the distribution of a given column is uniform.

**Value**

A copy of `x`, in which numerical columns have been discretised.

**Note**

While convenient, this function does not necessary provide optimal quantisation of the data (in terms of future `vistla` performance); especially the `bins` parameter should be adjusted to the input data, either via optimisation or based on the known properties of the input or mechanisms behind it.

**Examples**

```
## Not run:  
data(cchain)  
vistla(Y~., data=mle_coerce(cchain, 3, "size"))  
  
## End(Not run)
```

---

paths *List all paths*

---

### Description

Executes [path\\_to](#) for all path possible targets and returns a list with the results.

### Usage

```
paths(x, targets_only = !is.null(x$targets), detailed = FALSE)
```

### Arguments

x	vistla object.
targets_only	if TRUE, only paths to targets are extracted. By default, turned on when x has targets, and off otherwise.
detailed	passed to <a href="#">path_to</a> . If TRUE, suppresses default output and presents the same paths in a form of data frames featuring score.

### Value

A named list with one element per leaf or target, containing the path between this feature and root, in a format identical to this used by the [path\\_to](#) function.

---

path\_to *Extract a single path*

---

### Description

Gives access to a vector of feature names over a path to a certain target feature.

### Usage

```
path_to(x, target, detailed = FALSE)
```

### Arguments

x	vistla object.
target	target feature name.
detailed	if TRUE, suppresses default output and presents the same paths as a data frame featuring score.

### Value

By default, a character vector with names of features along the path from target into root. When detailed is set to TRUE, a `data.frame` in a format identical to this produced by [branches](#), yet without the leaf column.



## Description

Plots a vistla tree, using layout derived by a Buchheim et al. extension of the standard Reingold-Tilford method. The tree root is placed on the left, while the paths extend to the right, with all branches of the same depth at the same horizontal coordinate. The path are sorted vertically, from strongest on top to weakest on the bottom. Link weight indicates, by default, the link's score. A feature name in parentheses indicates that it is only a way-point in a path to some other feature.

## Usage

```
## S3 method for class 'vistla'
plot(
  x,
  ...,
  slant,
  circular,
  asp1 = FALSE,
  pmar = c(0.05, 0.05, 0.05, 0.05),
  edge_col = 1,
  edge_lwd = "scale",
  edge_lty = 1,
  label_text = function(x) x$name,
  label_border_col = 1,
  label_border_lty = function(x) ifelse(x$leaf, 1, 2),
  label_fill = "white"
)

## S3 method for class 'vistla_plot'
plot(x, ...)

## S3 method for class 'vistla_plot'
print(x, ...)
```

## Arguments

x	vistla, vistla hierarchy or vistla plot object.
...	ignored.
slant	arrange vertices in a slanted way. Can be given as a number, possibly negative, indicating the amount of slant, or as TRUE, for an auto value. No slant is applied when set to 0 or omitted.
circular	if given TRUE, switches to circular layout; alternatively, can be given two numbers, then the first one will be interpreted as an angle to fit the whole graph in ( $2\pi$ when using TRUE), and the second one as an initial angle offset (0 when

using TRUE), which can be used to rotate the whole graph around the root. Both angles are expected to be in radians. It is recommended to add asp=TRUE parameter to make this layout truly circular, otherwise lines of equal depth are going to be elliptical. When FALSE, linear layout is enforced.

asp1	if TRUE, scales on both axes are the same, like with asp=1 in base graphics.
pmar	Specifies margins as a fraction of graph size; expects a 4-element vector, in standard R bottom-left-top-right order.
edge_col	edge colour; can be given as vector, then mapping order adheres to the one in hierarchy object; please note that the edge towards first feature, the root, is not drawn, so the first element is effectively ignored. If given as a function, it is called on the internally generated extended hierarchy object, and the result is used as an aesthetic.
edge_lwd	edge width; behaves similarly to edge_col, yet also accepts special value 'scale', which triggers default scaling of edge width to be proportional to score.
edge_lty	edge line-type; behaves similarly to edge_col.
label_text	vertex label text, feature name by default. Behaves similarly to edge_col.
label_border_col	vertex label border colour; behaves similarly to edge_col, can be set to 0 for no border.
label_border_lty	vertex label border line-type; behaves similarly to edge_col, can be set to 0 for no border.
label_fill	vertex label fill colour; behaves similarly to edge_col, can be set to 0 for no fill.

**Value**

Grid object with the graph.

**Note**

The graph is rendered using the grid graphics system, in a manner similar to ggplot2; the output of the plot.vistla function is only a grid graphical object, while the actual plotting is done when this object is printed or plotted. Yet, said object can be used with other functions in the grid ecosystem for rendering into files, being edited, combined with other plots, etc.

**References**

"Drawing rooted trees in linear time" C. Buchheim, M. Jünger, S. Leipert. Software: Practice and Experience 36(6):651-665 (2006).

---

```
print.vistla_hierarchy
    Print vistla objects
```

---

**Description**

Utility functions to print vistla objects.

**Usage**

```
## S3 method for class 'vistla_hierarchy'
print(x, ...)

## S3 method for class 'vistla'
print(x, n = 7L, ...)
```

**Arguments**

x	vistla object.
...	ignored.
n	maximal number of paths to preview.

**Value**

Invisible copy of x.

---

```
prune    Prune the vistla tree
```

---

**Description**

This function allows to filter out suboptimal branches, as well as weak ones or these not in particular paths of interest.

**Usage**

```
prune(x, targets, iomin)
```

**Arguments**

x	vistla object.
targets	a character vector of features. When not missing, all branches not on lying paths to these targets are pruned. Unreachable targets are ignored, while names not present in the analysed set cause an error.
iomin	a single numerical value. When given, it effectively overrides the value of iomin given to the <code>vistla</code> invocation; to this end, it can only be higher than the original value, since <code>prune</code> only modifies the output and cannot re-run the pathfinding.

**Value**

Pruned x; if both arguments are missing, this function still removes suboptimal branches.

**Examples**

```
## Not run:
data(chain)
v<-vistla(Y~.,data=chain)
print(v)
print(prune(v,targets="M3"))
print(prune(v,iomin=0.3))

## End(Not run)
```

---

vistla

*Influence path identification with the Vistla algorithm*

---

**Description**

Detects influence paths.

**Usage**

```
vistla(x, ...)
```

## S3 method for class 'formula'

```
vistla(formula, data, ..., yn)
```

## S3 method for class 'data.frame'

```
vistla(
  x,
  y,
  ...,
  flow,
  iomin,
  targets,
  estimator = c("mle", "kt"),
  verbose = FALSE,
  yn = "Y",
  threads
)
```

## Default S3 method:

```
vistla(x, ...)
```

## Arguments

<code>x</code>	data frame of predictors.
<code>...</code>	pass-through arguments, ignored.
<code>formula</code>	alternatively, formula describing the task, in a form <code>root~predictors</code> , which adheres to standard R behaviours. Accepts <code>+</code> to add a predictor, <code>-</code> to omit one, and <code>.</code> to import whole data. Use <code>I</code> to calculate new predictors. When present in <code>data</code> , response is getting omitted from predictors.
<code>data</code>	<code>data.frame</code> in context of which the formula will be executed; can be omitted when not using <code>..</code>
<code>yn</code>	name of the root (Y value), used in result pretty-printing and plots. Must be a single-element character vector.
<code>y</code>	vistla tree root, a feature from which influence paths will be traced.
<code>flow</code>	algorithm mode, specifying the <code>iota</code> function which gives local score to an edge of an edge graph. If in doubt, use the default, <code>"fromdown"</code> .
<code>iomin</code>	score threshold below which path is not considered further. The higher value the less paths are generated, which also lowers the time taken by the function. The default value of 0 turns off this filtering. The same effect can be later achieved with the <code>prune</code> function.
<code>targets</code>	a vector of target feature names. If given, the algorithm will stop just after reaching the last of them, rather than after tracing all paths from the root. The same effect can be later achieved with the <code>prune</code> function. This is a simple method to remove irrelevant paths, yet it comes with a substantial increase in computational burden.
<code>estimator</code>	mutual information estimator to use. <code>"mle"</code> — maximal likelihood, requires all features to be discrete (factors or booleans). <code>"kt"</code> — Kendall transformation, requires all features to be either ordinal (numeric, integer or ordered factor) or bi-valued (two-level factors or booleans).
<code>verbose</code>	when set to <code>TRUE</code> , turns on reporting of the algorithm progress.
<code>threads</code>	number of threads to use. When missing or set to 0, vistla uses all available cores.

## Value

The tracing results represented as an object of a class `vistla`. Use `paths` and `path_to` functions to extract individual paths, `branches` to get the whole tree and `mi_scores` to get the basic score matrix.

## References

"Kendall transformation brings a robust categorical representation of ordinal data" M.B. Kursu. *SciRep* 12, 8341 (2022).

write.dot

*Export tree to a Graphviz DOT format***Description**

Exports the vistla tree in a DOT format, which can be later layouted and rendered by Graphviz programs like dot or neato.

**Usage**

```
write.dot(
  x,
  con,
  vstyle = list(shape = function(x) ifelse(x$depth < 0, "egg", ifelse(x$leaf, "box",
    "ellipse")), label = function(x) sprintf("\'%s\'", x$name)),
  estyle = list(penwidth = function(x) sprintf("%.3f", 0.5 + x$score/max(x$score) *
    2.5)),
  gstyle = list(overlap = "\'prism\'", splines = "true"),
  direction = c("none", "fromY", "intoY")
)
```

**Arguments**

x	vistla object.
con	connection; passed to writeLines. If missing, the DOT code is returned as a character vector.
vstyle	vertex attribute list — should be a named list of Graphviz attributes like shape or penwidth. For elements which are strings or numbers, the value is copied as is as an attribute value. For elements which functions, though, the function is called on a vistla_tree object and should return a vector of values.
estyle	edge attribute list, behaves exactly like vstyle. When functions are called, the Y-vertex is not present.
gstyle	graph attribute list. Functions are not supported here.
direction	when set to "none", graph is undirected, otherwise directed, for "fromY", root is a source, while for "intoY", a sink.

**Value**

For a missing con argument, a character vector with the graph in the DOT format, invisible NULL otherwise.

**Note**

Graphviz attribute values can be either strings, like "some vertex" in label, or atoms, like box for shape. When returning a string value, you must supply quotes, otherwise it will be included as an atom.

The default value of `gstyle` may invoke long layout calculations in Graphviz. Change to `list()` for a fast but less aesthetic layout.

The function does no validation whether provided attributes or values are correct.

### **References**

"An open graph visualization system and its applications to software engineering" E.R. Gansner, S.C. North. *Software: Practice and Experience* 30:1203-1233 (2000).

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